

# Numerical Python

CS101 lec11

Plotting

# Announcements

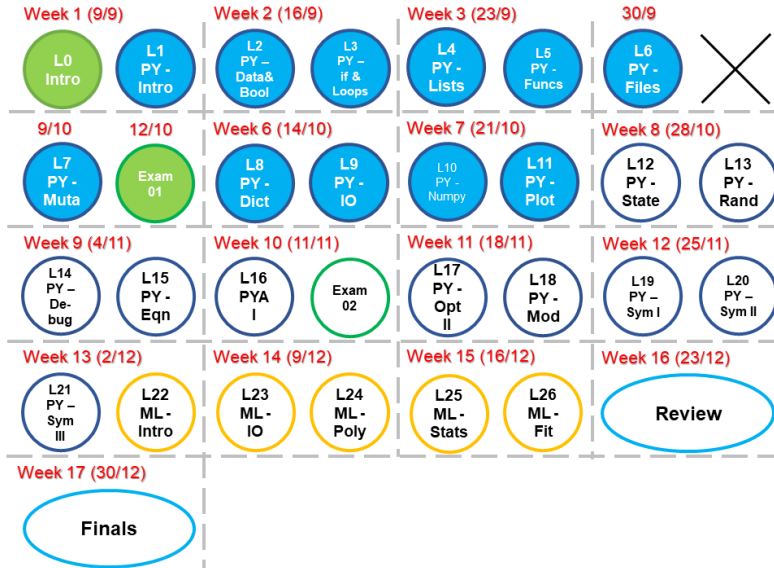
quiz: [quiz11](#) due on Thurs 24/10

lab: [lab](#) running in 100 meters race. No Lab

hw: [hw06](#) due Wed 30/10

exam: [exam02](#) coming in Nov

# Roadmap



# Objectives

- A. Create basic plots of several types using Matplotlib. => Using **lec10 Numpy** type as data
- B. Understand (and be able to repeat) the import process for Matplotlib.
- C. Display simulation results in an intelligible fashion as a plot. => Needed everywhere in Engineering

# numpy Recap

# Main point

0. In numpy, the operators and functions normally work element-wise

1. `x = np.zeros(5) = np.zeros((5)) = np.zeros([5])` creates a 1D np.array

2. You can only do `x[i]` where `i = 0 to 4`

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Compare with

3. `x = np.zeros([1,5]) = np.zeros((1,5))` creates a 2D np.array of 1 row and 2 columns

4. You can do `x[i,j]` where  $i = 0$  and  $j = 0$  to 4  
or `x[i]` where  $i = 0$  which shows the whole row

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\*\* 1D vs 2D array is true for other commands like  
`np.array([1,2,3])` vs `np.array([[1,2,3]])`

\*\* Use `([ ])` or `([[ ]])` to create array



# numpy

```
>>> x.max(i)
#max by column if i=0, by row if i=1
#max of everything in x if nothing

>>> x.min(i)
#min by column if i=0, by row if i=1
#min of everything in x if nothing

>>> x.mean(i)
#mean by column if i=0, by row if i=1
#mean of everything in x if nothing
```

# Question 1

$$x = \begin{pmatrix} 1 & 1 \\ 2 & 2 \\ 3 & 3 \end{pmatrix}$$

What will produce this array?

- A `np.array([[1,2,3],[1,2,3]])`
- B `np.array([2,3])`
- C `np.array([3,2])`
- D `np.array([[1,1],[2,2],[3,3]])`

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- B `np.array([2,3])`
- C `np.array([3,2])`
- D `np.array([[1,1],[2,2],[3,3]])` \*\*\*

## Question 2

$$x = \begin{pmatrix} 9 & 1 \\ 2 & 1 \\ 3 & 3 \end{pmatrix}$$

What will be

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2. `x.argsort(0)`

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$$x = \begin{pmatrix} 9 & 1 \\ 2 & 1 \\ 3 & 3 \end{pmatrix}$$

What will be

1. `x.sort(0)`? (by column)

$$x = \begin{pmatrix} 2 & 1 \\ 3 & 1 \\ 9 & 3 \end{pmatrix}$$

2. `x.argsort(0)`

$$\begin{pmatrix} 1 & 0 \\ 2 & 1 \\ 0 & 2 \end{pmatrix}$$

`x` NOT changed!

# Question 2

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4. `x.mean(1)` (by row)



## Question 2

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What will be

3. `x.sort(1)`? (by row)

$$x = \begin{pmatrix} 1 & 9 \\ 1 & 2 \\ 3 & 3 \end{pmatrix}$$

4. `x.mean(1)` (by row)

`array([5., 1.5, 5.])`

# Plotting

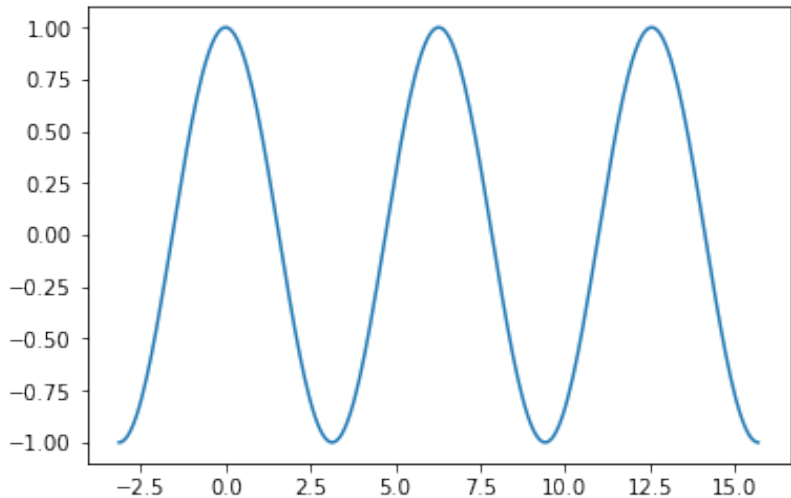
# Why plot?

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```
X = ([-3.14159265, -3.11695271, -3.09231277, -3.067
      -3.01839294, -2.993753    , -2.96911306, -2.94
      -2.89519323, -2.87055329, -2.84591335, -2.82
      ... (1000 lines)
      2.89519323,  2.91983317,  2.94447311,  2.96
      3.01839294,  3.04303288,  3.06767283,  3.14

Y = ([-1.          , -0.99969645, -0.99878599, -0.997
      -0.99242051, -0.98909161, -0.98516223, -0.98
      -0.96979694, -0.96349314, -0.95660442, -0.94
      ... (1000 lines)
      -0.96979694, -0.97551197, -0.98063477, -0.98
      -0.99242051, -0.99514692, -0.99726917, -1.]
```

# Why plot?



# matplotlib

```
import matplotlib.pyplot as plt  
# add this for jupyter only  
%matplotlib inline
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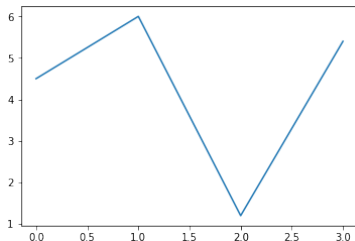
- > A plotting environment similar to MATLAB.
- > Can plot `lists`, `np.arrays` or most containers.

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%matplotlib inline
```

- > A plotting environment similar to MATLAB.
- > Can plot `lists`, `np.arrays` or most containers.

```
xs = list( range(4) )  
ys = [ 4.5, 6.0, 1.2, 5.4 ]  
plt.plot( xs, ys )  
plt.show()
```





One kind of plots today:

```
> plt.plot( x,y ) # for point-wise data
```

Basic cycle:

1. Add data to plot.
2. Plot.
3. Show plot.

Assuming you have a lot of data pairs  $X, C$  and  $X, S$  and  $X, Y$

**# Plot**

```
import matplotlib.pyplot as plt
plt.plot(X, C, color="blue", linewidth=1.0,
         linestyle="--", label="Solid")
plt.plot(X, S, color="red", linewidth=3,
         linestyle="--", label="Dot")
plt.plot(X, Y, 'ko', label="oo")
```

**# Set x and y limits for display**

```
plt.xlim(-4.0, 4.0)
plt.ylim(-1.0, 1.0)
```

**# Set x and y ticks intervals**

```
plt.xticks(np.linspace(-4, 4, 9, endpoint=True))
plt.yticks(np.linspace(-1, 1, 5, endpoint=True))
```

**# Adding x-axis and y-axis labels and a title**

```
plt.xlabel( 't (s)' )  
plt.ylabel( 'Value (NA)' )  
plt.title( 'Three Curves' )
```

**# Adding a legend**

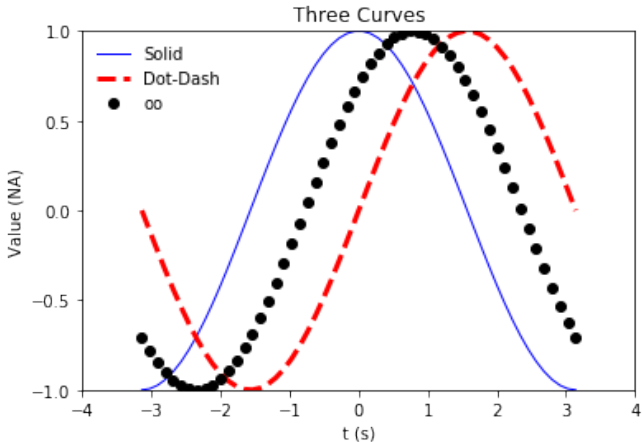
```
plt.legend(loc='upper left', frameon=False)
```

**# Save figure using 72 dots per inch**

```
plt.savefig("filePath/ex2.png", dpi=72)
```

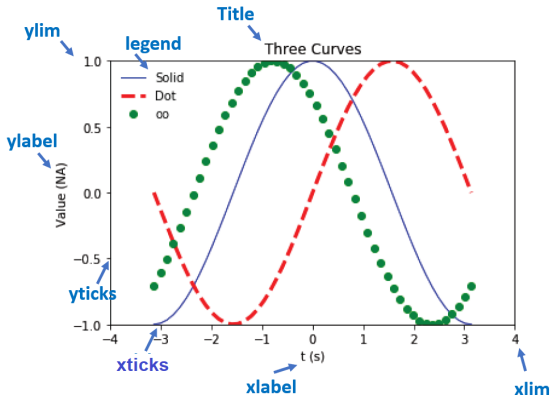
**# Show result on screen**

```
plt.show()
```



Where are the `xlim`, `ylim`, `legend`, `xticks`, `yticks`, `title`, `xlabel`, `ylabel`?

You have plotted an invisible graph  
if you see it, you have x-ray eyes  
if not, move to the next page for your answers



Note: The xlim and ylim refers to both ends.  
xticks give the positions of interval across x-axis

*Always* include labels:

```
> plt.xlabel( 'domain (units)' )
```

```
> plt.ylabel( 'range (units)' )
```

```
> plt.title( 'topical data' )
```

(We may omit this in lecture for convenience.)

```
plt.plot( xs, ys )
```

```
plt.xlabel( 'x' )
```

```
plt.ylabel( 'y' )
```

```
plt.title( 'some values' )
```

```
plt.show()
```



# Why use numpy as input?

**Plot  $\sin(x)$  for  $x \in [0, 2\pi]$**

## 1. Pure Python:

```
from math import pi
x = [] # can't use range easily!
for i in range(100):
    x.append( 2*pi*i/100 )
from math import sin
y = []
for j in range(100):
    y.append( sin(x[j]) )

plt.plot( x,y,'k-' )
plt.xlim( 0,2*pi )
plt.ylim( -1,1 )
plt.show()
```

# Why use numpy as input?

**Plot  $\sin(x)$  for  $x \in [0, 2\pi]$**

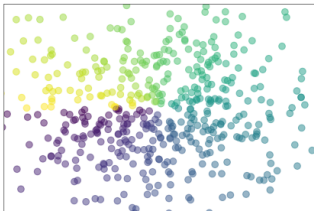
2. numpy:

```
import numpy as np
x = np.linspace( 0, 2*np.pi, 101 )
y = np.sin( x )

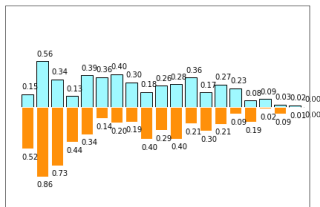
plt.plot( x, y, 'k-' )
plt.xlim( 0, 2*pi )
plt.ylim( -1, 1 )
plt.show()
```

# Other than .plot ?

> `.scatter` - plot of points (x,y)

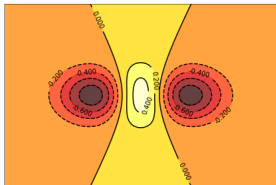


> `.bar` - bar chart

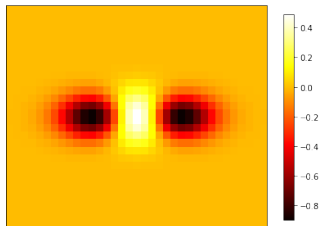


# Other plot types?

- > `.contour` - identical values are connected together.  
Like in a physical map

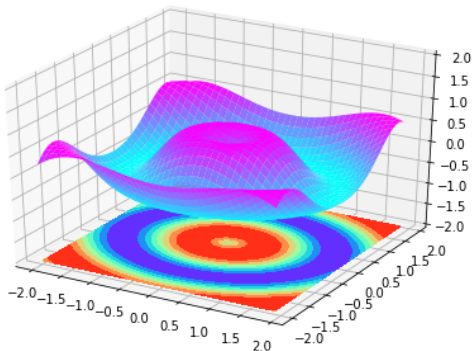


- > `.imshow` - show an image or plot a collection of values  
in one array



# Other plot types?

> `.plot_surface` - plot of a 3D surface



> animation

# Modeling (next lecture)

# Modeling

Help to simplify a complicated problem

Based on mathematical equations and physical laws

Gives an "Ideal" solution

But... it is not EXACTLY correct!

# Modeling

"All models are wrong but some are useful"  
~ George Box



# Modeling

Consider a ball falling from the edge of a table. Describe its path and time until it hits the ground.

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Consider a ball falling from the edge of a table. Describe its path and time until it hits the ground.

Two approaches:

- A Use analytical equation (if available).
- B Use finite difference equation otherwise.

# Modeling

A Use analytical equation (if available).

$$y(t) = y_0 + v_0 t + \frac{a}{2} t^2$$

$$y_0 = 1$$

$$v_0 = 0$$

$$a = -9.8$$

subject to

$$y(t) \geq 0$$

# Modeling

```
import numpy as np

# Parameters of simulation
n = 100      # number of data points to plot
start = 0.0  # start time, s
end = 1.0    # ending time, s
a = -9.8     # acceleration, m*s**-2

# State variable initialization
t = np.linspace(start, end, n+1) # time, s

y = 1.0 + a/2 * t**2

for i in range(1, n+1):
    if y[i] <= 0: # ball has hit the ground
        y[i] = 0
```

# Modeling

A Use “finite difference” equation otherwise.

# Modeling

A Use “finite difference” equation otherwise.

$$\frac{dy}{dt} = v(t) \approx \frac{y^{n+1} - y^n}{t^{n+1} - t^n} \rightarrow y^{n+1} = y^n + v(t^{n+1} - t^n)$$

$$\frac{dv}{dt} = a \approx \frac{v^{n+1} - v^n}{t^{n+1} - t^n} \rightarrow v^{n+1} = v^n + a(t^{n+1} - t^n)$$

$$v^{n=0} = 0 \qquad y^{n=0} = 1 \qquad a = -9.8$$

subject to

$$y(t) \geq 0$$

# Modeling

	0	1	...	$i-1$	$i$	$i+1$	...	$n$
t	0.0	0.1	...	...	...	...	...	1.0
y	1.0	0.9	...	...	...	...	0.0	0.0
v	0.0	0.1	...	...	...	...	0.0	0.0

# Modeling

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# Parameters of simulation
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start = 0.0  # start time, s
end = 1.0    # ending time, s
a = -9.8     # acceleration, m*s**-2

# State variable initialization
t = np.linspace( start,end,n+1 )      # time, s
y = np.zeros( n+1 )                   # height, m
v = np.zeros( n+1 )                   # velocity, m*s**-1
y[ 0 ] = 1.0                           # initial condition, m

for i in range( 1,n+1 ):
    v[ i ] = v[ i-1 ] + a*( t[ i ]-t[ i-1 ] )
    y[ i ] = y[ i-1 ] + v[ i ] * ( t[ i ]-t[ i-1 ] )

    if y[ i ] <= 0: # ball has hit the ground
        v[ i ] = 0
        y[ i ] = 0
```



# Modeling

A How would you make the ball bounce?

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- B How would you include lateral motion?

# Modeling

- A How would you make the ball bounce? (Reverse the direction of the velocity at the ground; have a decay factor.)
- B How would you include lateral motion? (Have separate  $x$ - and  $y$ -positions and velocities.)